

Improving communication using 3D animation

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Motivations

Since ancient time the language has been seen as limited for communication

“The soul never thinks without a mental image” [Aristotle, de anima]

3D animations are now here to help communicate our ideas using an animation language

Why animation? A simple example

Mary walks away from the school



Why animation? A simple example

Mary walks away from the school



Previous work

- Animated Storytelling System via Text , *Kaoru & al, 2006 (children stories)*
- Word's Eye , *Coyne & al, 2001 (static scenes)*
- Automatic Conversion of Natural Language to 3D Animation , *Ma , 2006 (human action centered)*

The GITAN project

- Grammaire pour l'Interprétation de Texte en ANimation
- Is a 4 years project
- Has started in September 2009
- Is a collaboration between UnimaSoft and Ecole Polytechnique de Montréal.
- Has an application domain: teaching English as a second language (Chinese students).

The GITAN project, its goals

- Uses narrative sentences to describe complex scenes
- Contains a minimum set of animations and geometries
- Generates rich scenes, but no game-like realism
- Will provide a robust set of prototypes to the funding company
- Will develop a framework for 3D objects aggregation using the linked data paradigm

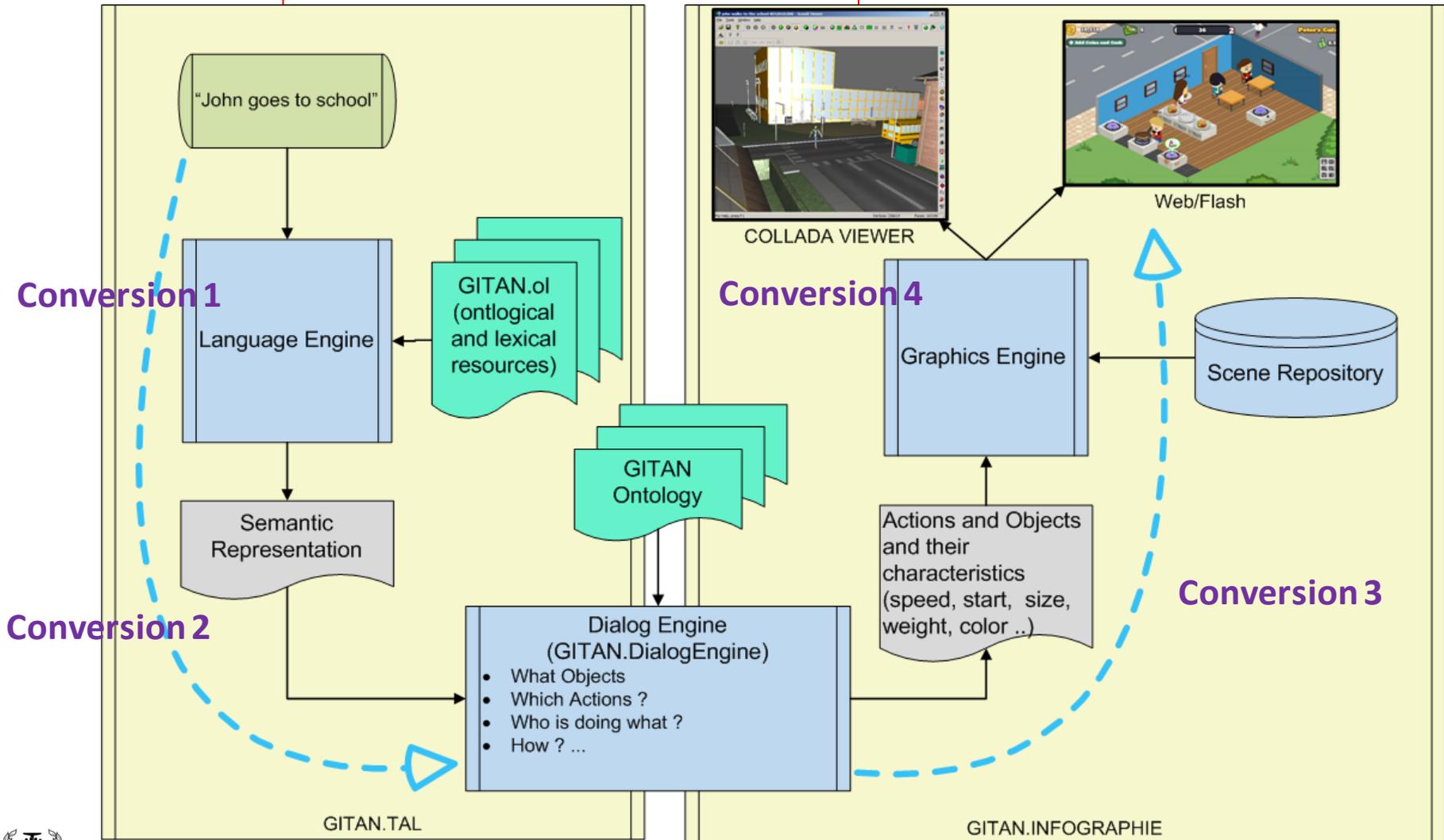
How ?

- We will use a waterfall model.
- Each module will gradually convert the text into an animation
- We are planning 4 different levels of 'conversion'

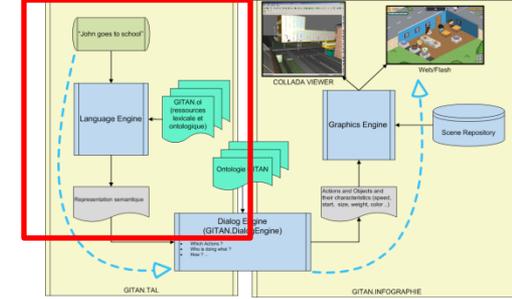
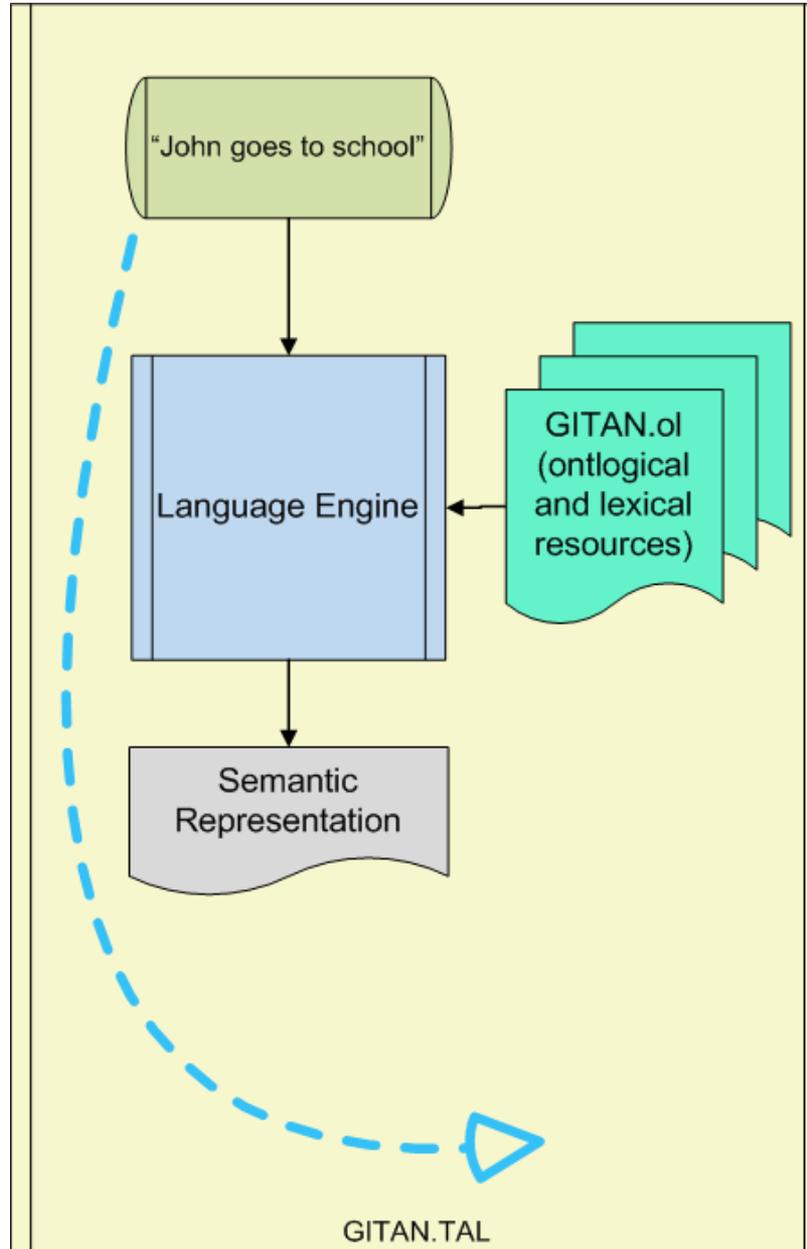


How ?

WARNING ! Things may change during the development phase



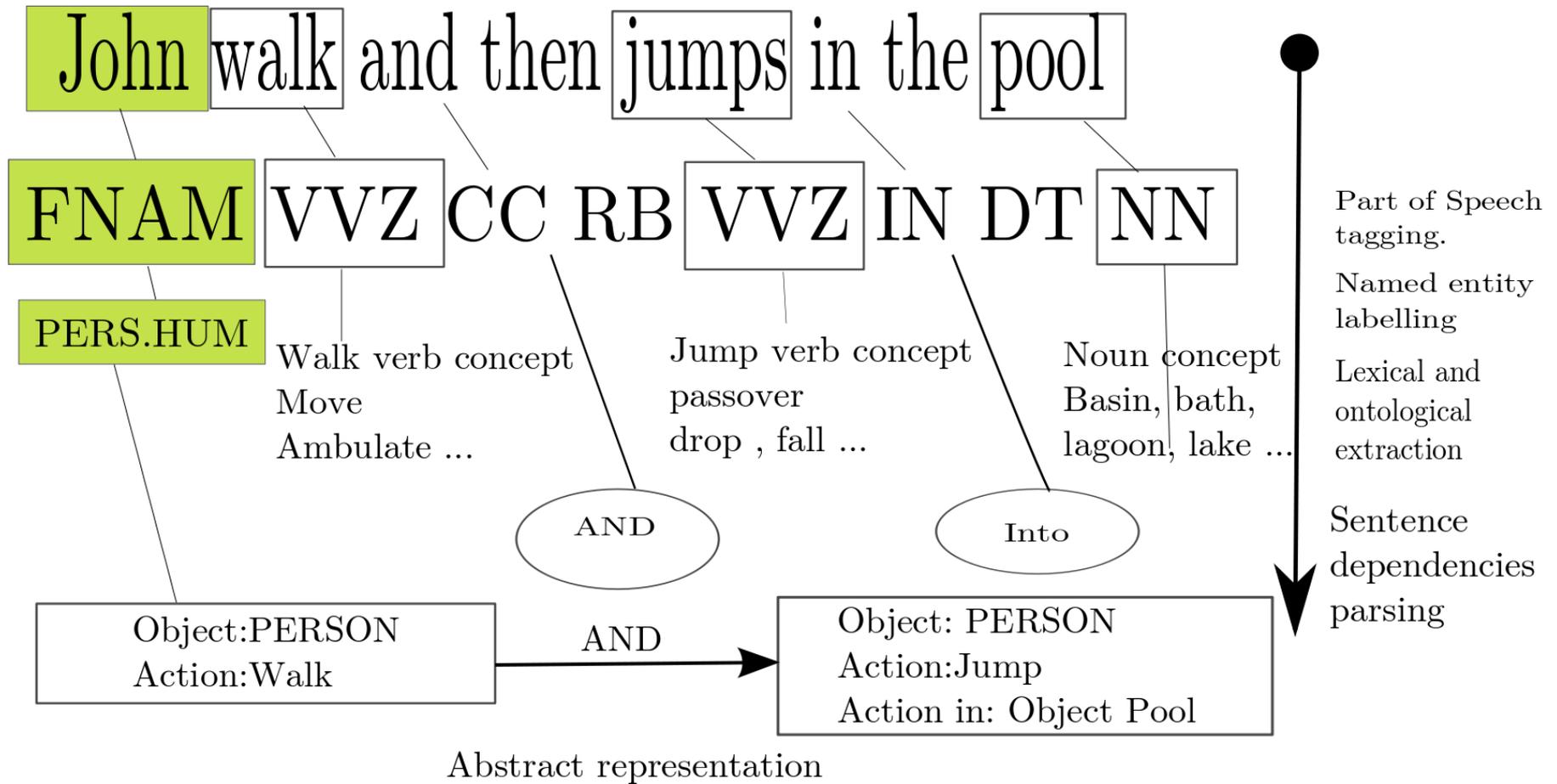
The Language Engine



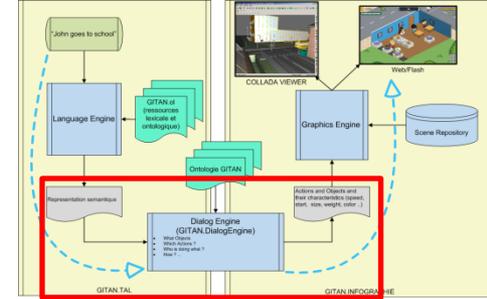
The Language Engine

Sentence representation

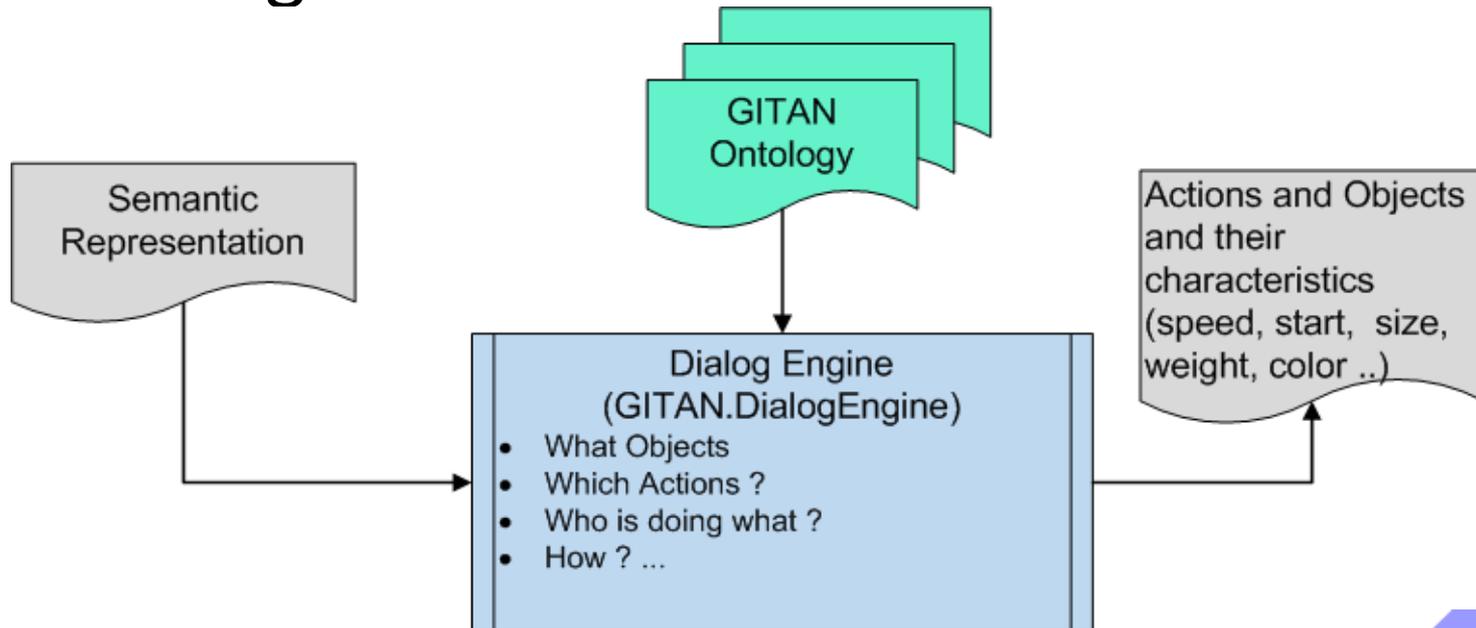
NLP task



The Dialog Engine



- Queries the ontologies and the concepts
- Produces an organized set of rules describing the scene

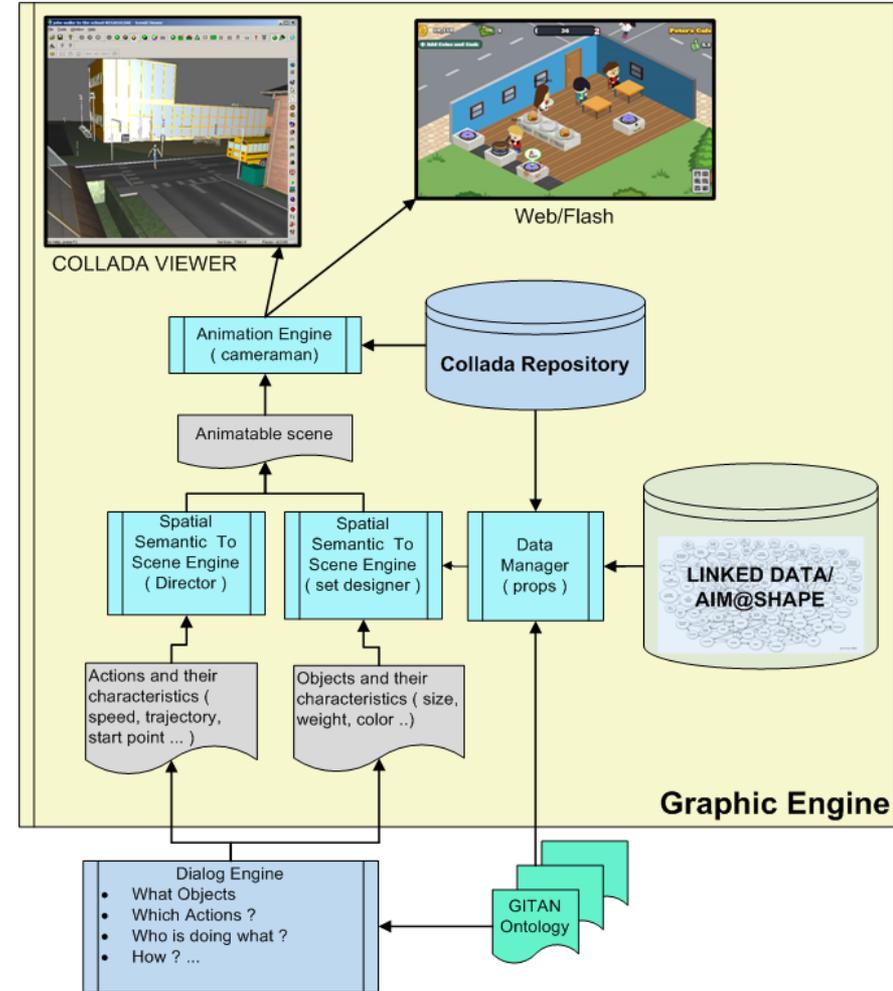


The Dialog Engine : the output text

- Is a textual description of the objects in the scene and their actions
- Makes the links between the Natural Language Processing world and the computer graphics world
- This is Work In Progress

The Graphic Engine

- Processes the results of the Dialog Engine
- Creates the animation displayed in a standard viewer
- Is made of 3 important parts

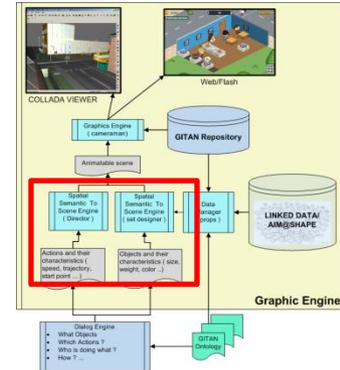
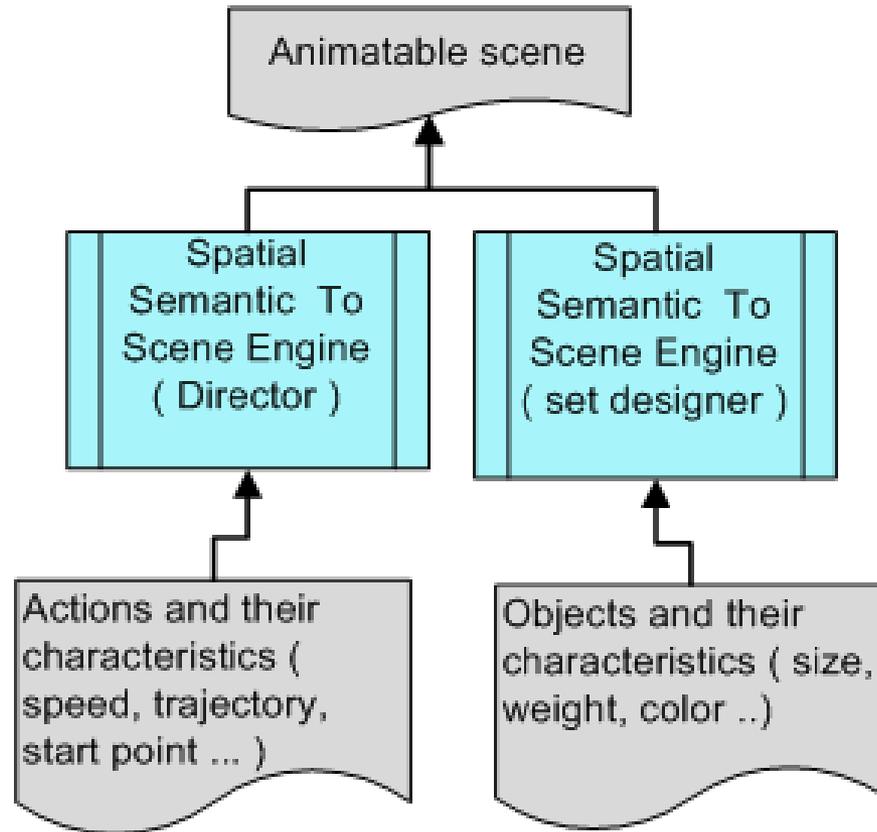


The Spatial Semantic to Scene Engine

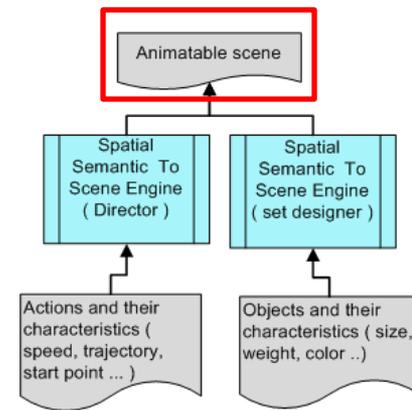
- Inserts the proper **geometries** and resolves all collisions issues.
- Implement the **animations**
- Uses ontologies for building a proper scene description (keyframe/transition concept).

The Spatial Semantic to Scene Engine

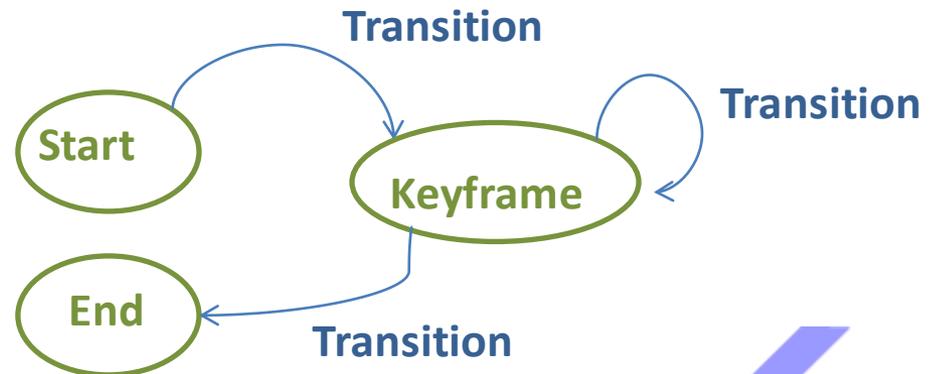
- Director
- Set Designer



The Animatable scene

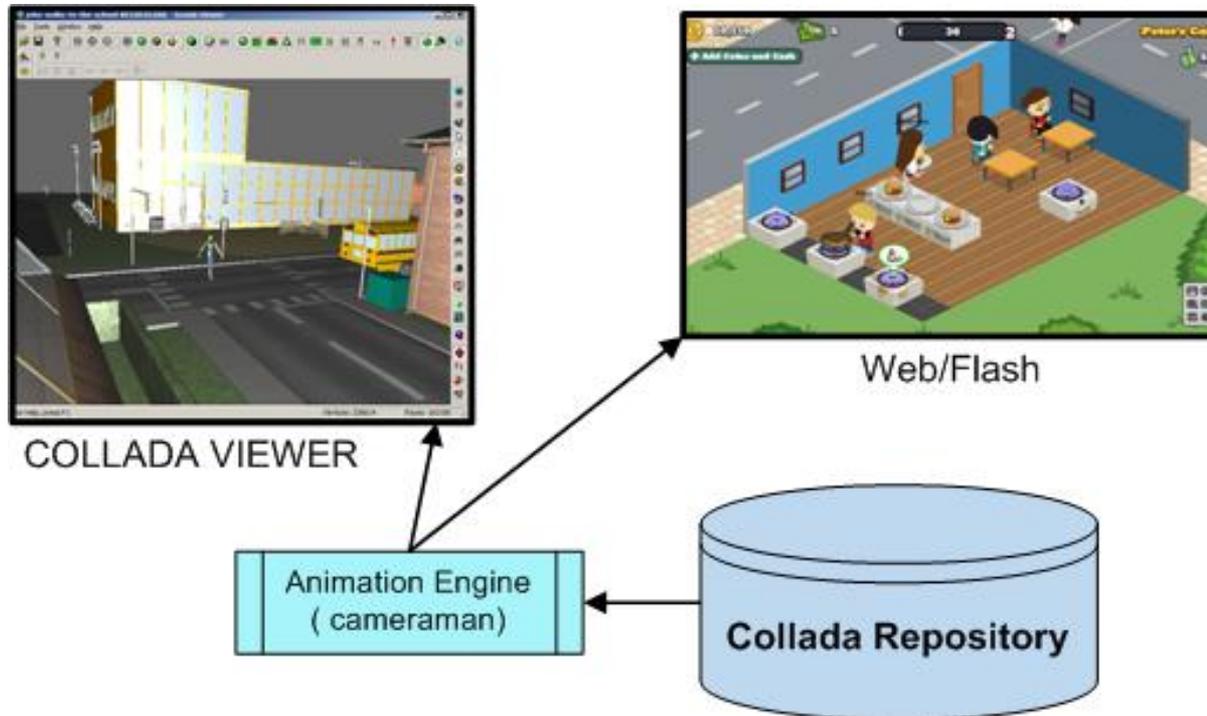
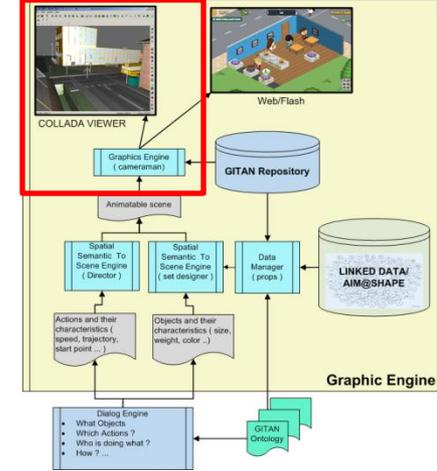


- Is the link between the Text To Scene engine and the Graphics Engine
- Defines a high level scene description
- Is Keyframe/Transition based



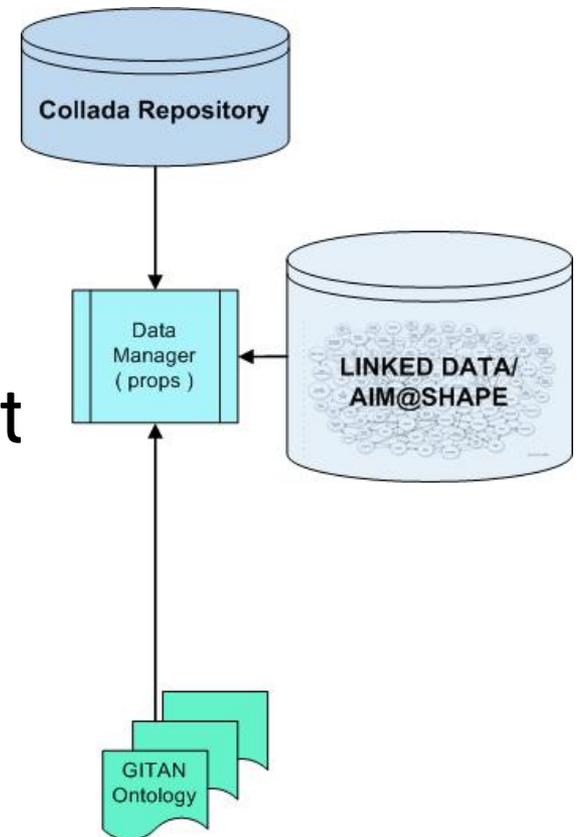
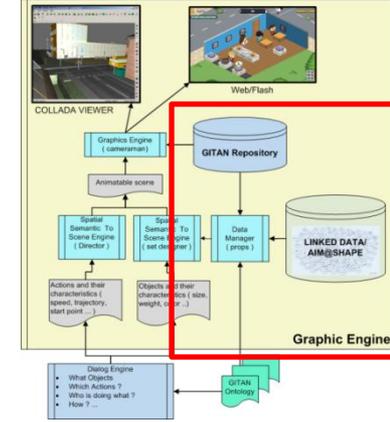
The Animation Engine

- Uses device independent scene description
- Consumes and produces a Collada file

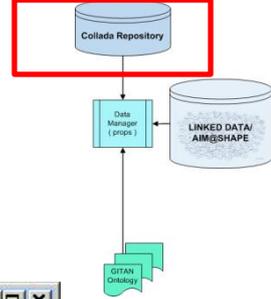


The Data manager

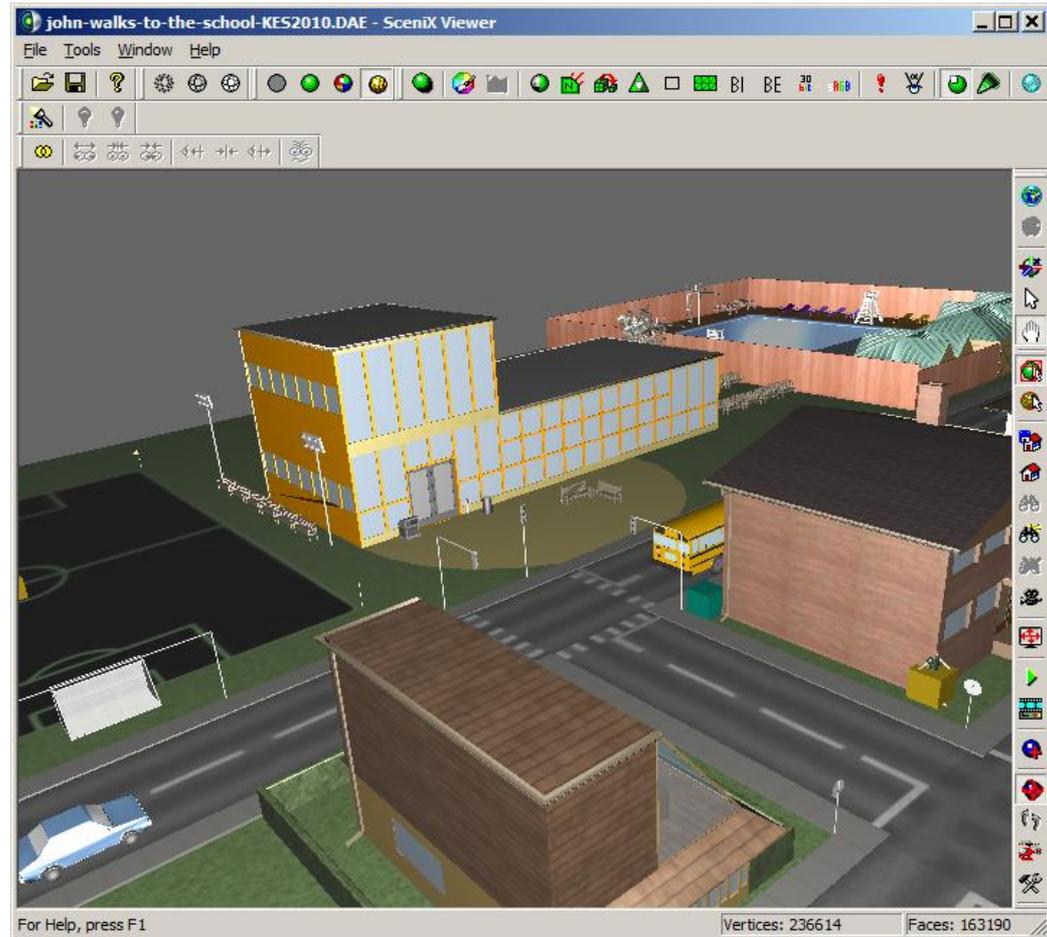
- Named geometries
- Categorized animations
- Minimalistic set of entries
- Connected to the web
- Using the Linked Data concept



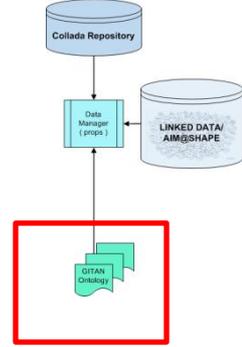
The Collada Repository



- It is a graphical standard file format
- Many software and institutions support it.



Ontologies for GITAN



- “Defines a set of representational primitives with which to model a domain of knowledge or discourse”, Gruber 2009
- Enables knowledge sharing and reuse.
- GITAN will develop its own ontology and anchor it to previous ontologies (GUM, Framenet,...)

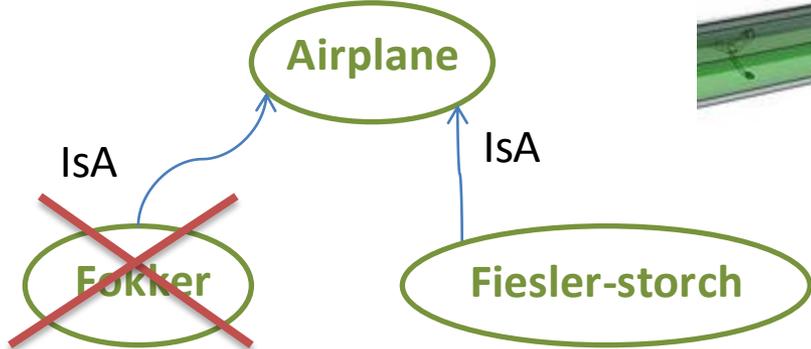
Ontologies in GITAN, an example



Fokker



Fiesler-storch



Demo: the Animation Engine

- We wanted to make sure that we could compose various animations
- Those are the first tests using hand made animatable scene files



Future work (short term)

- Develop the Dialog Engine. This is key
- Refine the Graphics Engine
- Enrich the repository
- Streamline the production of 3D objects



Future work (long term)

- Anchor the ontology of animation to other ontologies
- Support more than action verbs
- Streamline the geometry production
- Open GITAN to the web



Conclusions

- GITAN will help alleviate the limitations of the text
- We want to provide the community with an animation ontology, which can be applied to many domains
- GITAN has very ambitious goals
- We are not there yet !



Thank YOU and :

- PROMPT (funding agency from the Quebec government)
- UnimaSoft (private company planning to integrate this research in its future releases).

Those slides (and the paper) will be made available on :

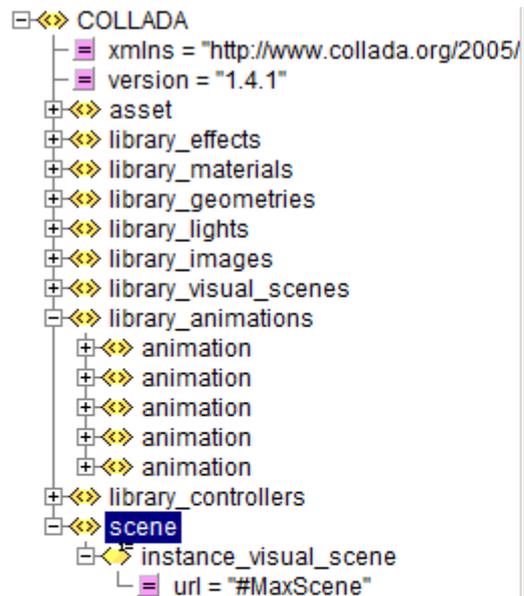
<http://www.groupees.polymtl.ca/gitan/index.php/fr/publications.html>

Questions ? (a 'Gitan' is a gipsy in English !)



The Graphics Engine

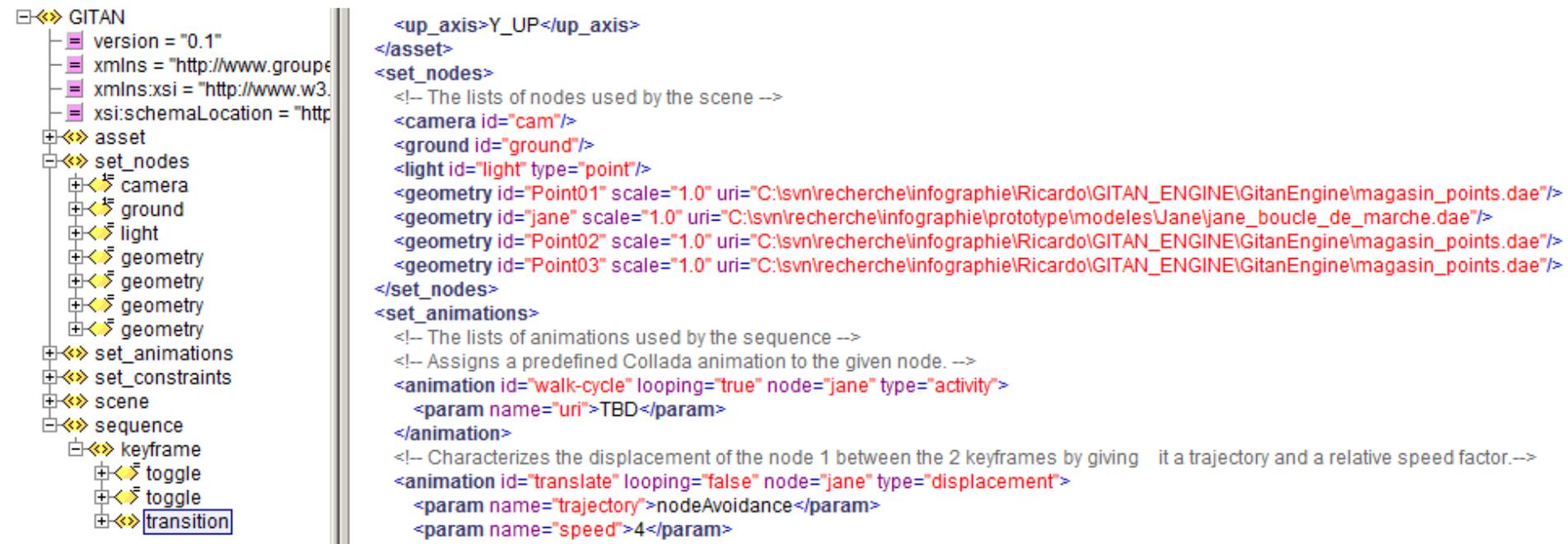
- Parses it and build the Collada file



```
<param name="TRANSFORM" type="float4x4" />
</accessor>
</technique_common>
</source>
<source id="geom-Jane_mesh-skin1-weights">
  <float_array id="geom-Jane_mesh-skin1-weight" />
  <technique_common>
    <accessor count="13214" source="#geom-Jar" />
    <param name="WEIGHT" type="float" />
  </accessor>
</technique_common>
</source>
<joints>
  <input semantic="JOINT" source="#geom-Jane_" />
  <input semantic="INV_BIND_MATRIX" source="#" />
</joints>
<vertex_weights count="6138">
  <input offset="0" semantic="JOINT" source="#ge" />
  <input offset="1" semantic="WEIGHT" source="#" />
  <vcount />
  <v />
</vertex_weights>
</skin>
</controller>
</library_controllers>
<scene>
  <instance_visual_scene url="#MaxScene" />
</scene>
</COLLADA>
```

The Graphics Engine

- Reads in the XML file



```
<!-- The lists of nodes used by the scene -->
<camera id="cam"/>
<ground id="ground"/>
<light id="light" type="point"/>
<geometry id="Point01" scale="1.0" uri="C:\svn\recherche\infographie\Ricardo\GITAN_ENGINE\GitanEngine\magasin_points.dae"/>
<geometry id="jane" scale="1.0" uri="C:\svn\recherche\infographie\prototype\modeles\Jane\jane_boucle_de_marche.dae"/>
<geometry id="Point02" scale="1.0" uri="C:\svn\recherche\infographie\Ricardo\GITAN_ENGINE\GitanEngine\magasin_points.dae"/>
<geometry id="Point03" scale="1.0" uri="C:\svn\recherche\infographie\Ricardo\GITAN_ENGINE\GitanEngine\magasin_points.dae"/>
</set_nodes>
<set_animations>
<!-- The lists of animations used by the sequence -->
<!-- Assigns a predefined Collada animation to the given node. -->
<animation id="walk-cycle" looping="true" node="jane" type="activity">
  <param name="uri">TBD</param>
</animation>
<!-- Characterizes the displacement of the node 1 between the 2 keyframes by giving it a trajectory and a relative speed factor.-->
<animation id="translate" looping="false" node="jane" type="displacement">
  <param name="trajectory">nodeAvoidance</param>
  <param name="speed">4</param>
</animation>
</set_animations>
```